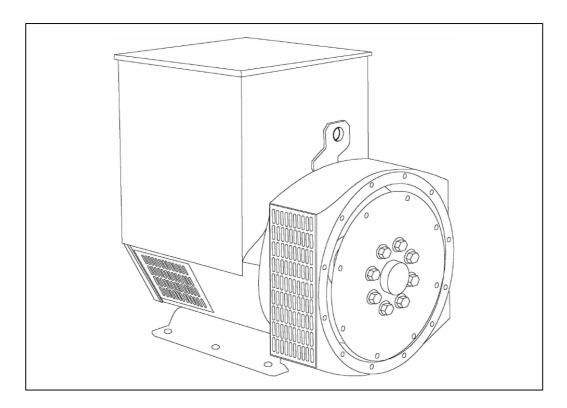


# **STAMFORD**

### UCI224D - Technical Data Sheet



### **SPECIFICATIONS & OPTIONS**



#### **STANDARDS**

Newage Stamford industrial generators meet the requirements of BS EN 60034 and the relevant section of other international standards such as BS5000, VDE 0530, NEMA MG1-32, IEC34, CSA C22.2-100, AS1359. Other standards and certifications can be considered on request.

### **VOLTAGE REGULATORS**

#### **SX460 AVR - STANDARD**

With this self excited control system the main stator supplies power via the Automatic Voltage Regulator (AVR) to the exciter stator. The high efficiency semiconductors of the AVR ensure positive build-up from initial low levels of residual voltage.

The exciter rotor output is fed to the main rotor through a three phase full wave bridge rectifier. This rectifier is protected by a surge suppressor against surges caused, for example, by short circuit.

#### SX440 AVR

With this self-excited system the main stator provides power via the AVR to the exciter stator. The high efficiency semi-conductors of the AVR ensure positive build-up from initial low levels of residual voltage.

The exciter rotor output is fed to the main rotor through a three-phase full-wave bridge rectifier. The rectifier is protected by a surge suppressor against surges caused, for example, by short circuit or out-of-phase paralleling.

The SX440 will support a range of electronic accessories, including a 'droop' Current Transformer (CT) to permit parallel operation with other ac generators

If 3-phase sensing is required with the self-excited system, the SX421 AVR must be used.

### SX421AVR

This AVR also operates in a self-excited system. It combines all the features of the SX440 with, additionally, three-phase rms sensing for improved regulation and performance. Over voltage protection is provided via a separate circuit breaker. An engine relief load acceptance feature is built in as standard.

### MX341 AVR

This sophisticated AVR is incorporated into the Stamford Permanent Magnet Generator (PMG) control system.

The PMG provides power via the AVR to the main exciter, giving a source of constant excitation power independent of generator output. The main exciter output is then fed to the main rotor, through a full wave bridge, protected by a surge suppressor. The AVR has in-built protection against sustained over-excitation, caused by internal or external faults. This de-excites the machine after a minimum of 5 seconds.

An engine relief load acceptance feature can enable full load to be applied to the generator in a single step.

If three-phase sensing is required with the PMG system the MX321 AVR must be used.

We recommend three-phase sensing for applications with greatly unbalanced or highly non-linear loads.

#### MX321 AVR

The most sophisticated of all our AVRs combines all the features of the MX341 with, additionally, three-phase rms sensing, for improved regulation and performance. Over voltage protection is built-in and short circuit current level adjustments is an optional facility.

#### WINDINGS & ELECTRICAL PERFORMANCE

All generator stators are wound to 2/3 pitch. This eliminates triplen (3rd, 9th, 15th ...) harmonics on the voltage waveform and is found to be the optimum design for trouble-free supply of non-linear loads. The 2/3 pitch design avoids excessive neutral currents sometimes seen with higher winding pitches, when in parallel with the mains. A fully connected damper winding reduces oscillations during paralleling. This winding, with the 2/3 pitch and carefully selected pole and tooth designs, ensures very low waveform distortion.

#### **TERMINALS & TERMINAL BOX**

Standard generators are 3-phase reconnectable with 12 ends brought out to the terminals, which are mounted on a cover at the non-drive end of the generator. A sheet steel terminal box contains the AVR and provides ample space for the customers' wiring and gland arrangements. It has removable panels for easy access.

### **SHAFT & KEYS**

All generator rotors are dynamically balanced to better than BS6861:Part 1 Grade 2.5 for minimum vibration in operation. Two bearing generators are balanced with a half key.

### INSULATION/IMPREGNATION

The insulation system is class 'H'.

All wound components are impregnated with materials and processes designed specifically to provide the high build required for static windings and the high mechanical strength required for rotating components.

### **QUALITY ASSURANCE**

Generators are manufactured using production procedures having a quality assurance level to BS EN ISO 9001.

The stated voltage regulation may not be maintained in the presence of certain radio transmitted signals. Any change in performance will fall within the limits of Criteria 'B' of EN 61000-6-2:2001. At no time will the steady-state voltage regulation exceed 2%.

NB Continuous development of our products entitles us to change specification details without notice, therefore they must not be regarded as binding.

Front cover drawing typical of product range.



### **WINDING 311**

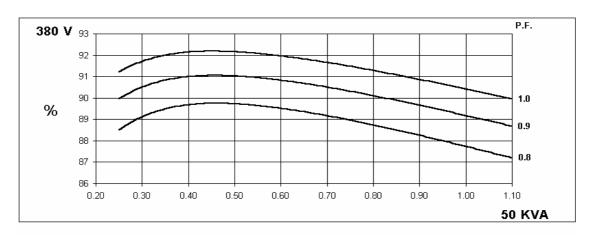
CONTROL SYSTEM	SEPARATEL	Y EXCITED I	BY P.M.G.						
A.V.R.	MX321	MX341							
VOLTAGE REGULATION	± 0.5 %	± 1.0 %	With 4% EN	GINE GOVER	RNING				
SUSTAINED SHORT CIRCUIT	REFER TO S	SHORT CIRC	UIT DECRE	MENT CURVE	ES (page 7)				
CONTROL SYSTEM	SELF EXCIT	ED							
A.V.R.	SX460	SX440	SX421						
VOLTAGE REGULATION		± 1.0 %	± 0.5 %	\\/ith 40/ ENI		DNING			
	± 1.5 %								
SUSTAINED SHORT CIRCUIT	SERIES 4 CO	JNTROL DO	ES NOT SU	STAIN A SHU	RT CIRCUIT	CURRENT			
INSULATION SYSTEM	CLASS H								
PROTECTION				IP2	23				
RATED POWER FACTOR				0.	8				
STATOR WINDING			DC	UBLE LAYER	CONCENTE	RIC			
WINDING PITCH				TWO T	HIRDS				
WINDING LEADS				1:	2				
STATOR WDG. RESISTANCE		0.129 (	Ohms PER P	HASE AT 22°	C SERIES S	TAR CONNE	CTED		
ROTOR WDG. RESISTANCE				0.64 Ohms	s at 22°C				
EXCITER STATOR RESISTANCE				21 Ohms	at 22°C				
EXCITER ROTOR RESISTANCE			0.07	1 Ohms PER	PHASE AT 2	2°C			
R.F.I. SUPPRESSION	RS EN	J 61000-6-2 8		00-6-4,VDE 0			factory for o	there	
	DO EI			*	*			uicis	
WAVEFORM DISTORTION		NO LOAD <	1.5% NON	-DISTORTING		LINEAR LO	AD < 5.0%		
MAXIMUM OVERSPEED				2250 R					
BEARING DRIVE END				BALL. 6312-	. ,				
BEARING NON-DRIVE END		4.554	DINIO	BALL. 6309-	-2RS (ISO)	0.054	DINIO.		
WEIGHT COMP. CENEDATOR			RING			2 BEA			
WEIGHT COMP. GENERATOR WEIGHT WOUND STATOR			kg kg			290 86			
WEIGHT WOUND STATOR WEIGHT WOUND ROTOR			8 kg			77.9	•		
WR2 INERTIA			6 kgm <sup>2</sup>			0.4198			
SHIPPING WEIGHTS in a crate			' kg			311			
PACKING CRATE SIZE		92 x 57				92 x 57 x			
		50	Hz			60	Hz		
TELEPHONE INTERFERENCE		THF	<2%		TIF<50				
COOLING AIR		0.216 m³/se	ec 458 cfm	1	0.281 m³/sec 595 cfm				
VOLTAGE SERIES STAR	380/220	400/231	415/240	440/254	416/240	440/254	460/266	480/277	
VOLTAGE PARALLEL STAR	190/110	200/115	208/120	220/127	208/120	220/127	230/133	240/138	
VOLTAGE SERIES DELTA kVA BASE RATING FOR REACTANCE	220/110	230/115	240/120	254/127	240/120	254/127	266/133	277/138	
VALUES	50	50	50	48	60	62.5	62.5	65	
Xd DIR. AXIS SYNCHRONOUS	2.33	2.10	1.95	1.67	3.04	2.83	2.59	2.47	
X'd DIR. AXIS TRANSIENT	0.18	0.16	0.15	0.13	0.22	0.20	0.19	0.18	
X"d DIR. AXIS SUBTRANSIENT	0.12	0.11	0.10	0.09	0.15	0.14	0.13	0.12	
Xq QUAD. AXIS REACTANCE X"q QUAD. AXIS SUBTRANSIENT	1.07 0.14	0.97	0.90	0.77	1.40 0.14	1.30	1.19	1.14	
XL LEAKAGE REACTANCE	0.14		0.12	0.10	0.14	0.13	0.12	0.11	
X2 NEGATIVE SEQUENCE	0.07	0.06	0.06	0.05	0.09	0.08	0.08	0.07	
X <sub>0</sub> ZERO SEQUENCE	0.13	0.12	0.11	0.09	0.09	0.13	0.12	0.11	
REACTANCES ARE SATURAT				PER UNIT A					
T'd TRANSIENT TIME CONST.		v	. LOLO AINL	0.02		.5 TOLINGE			
T"d SUB-TRANSTIME CONST.				0.00	16 s				
T'do O.C. FIELD TIME CONST.				0.7					
Ta ARMATURE TIME CONST.				0.00					
SHORT CIRCUIT RATIO				1/>	Ka				

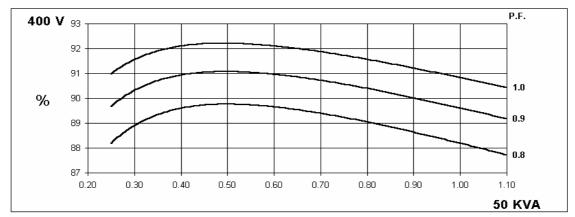
50 Hz

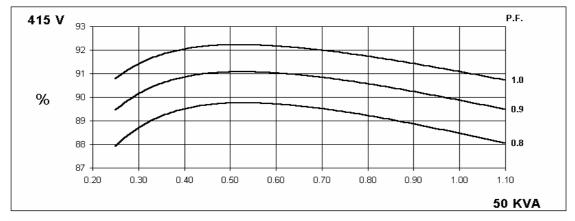
### UCI224D Winding 311

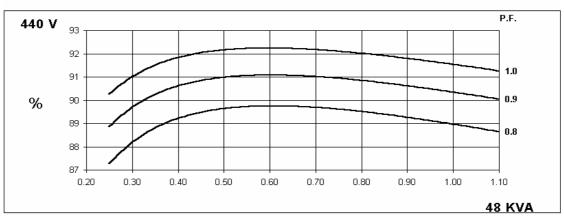


### THREE PHASE EFFICIENCY CURVES







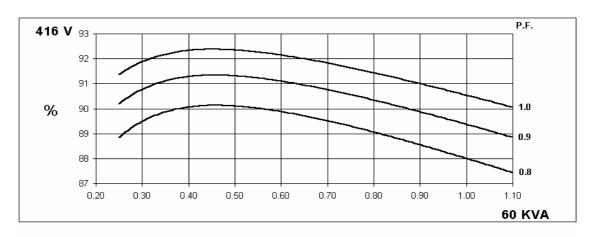


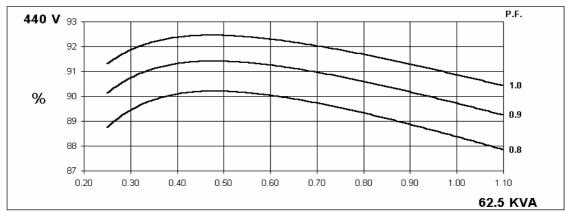


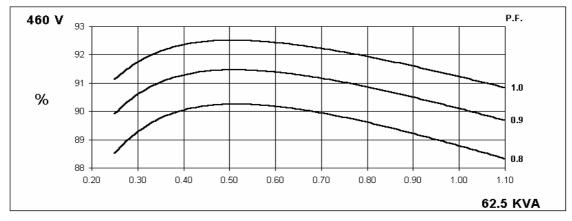
### UCI224D Winding 311

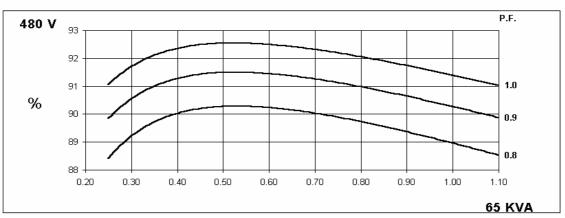
60 Hz

### THREE PHASE EFFICIENCY CURVES





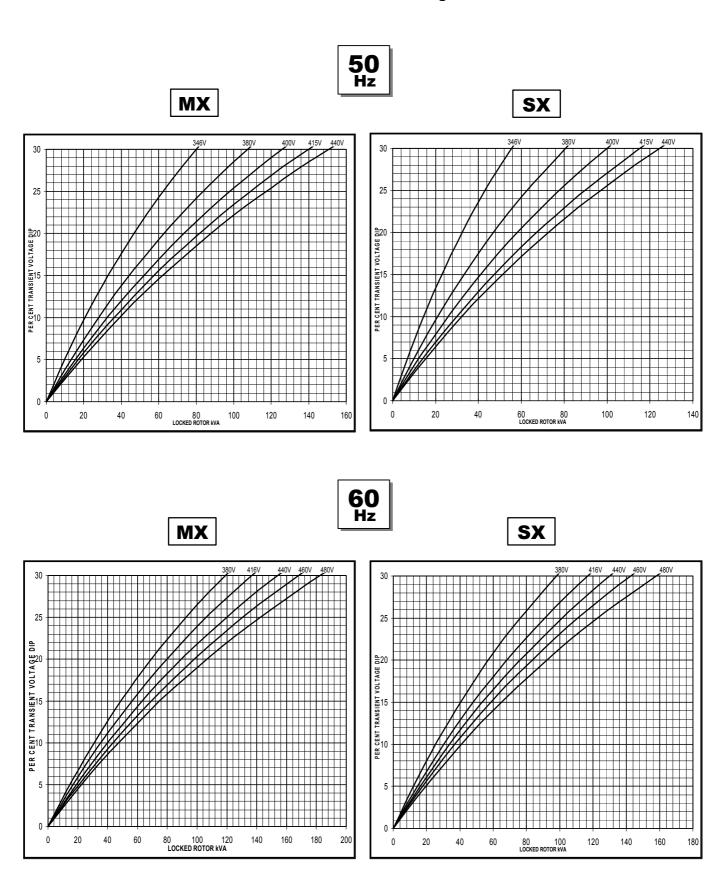




### UCI224D Winding 311



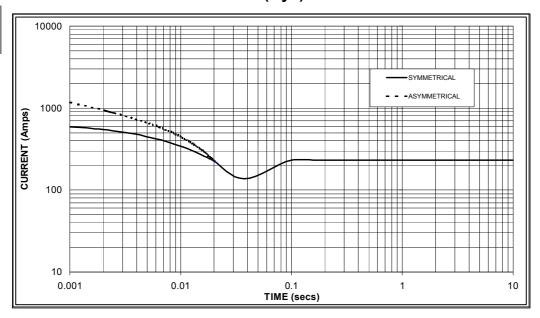
### **Locked Rotor Motor Starting Curve**





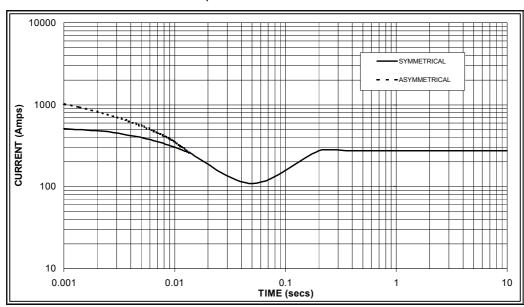
## Three-phase Short Circuit Decrement Curve. No-load Excitation at Rated Speed Based on star (wye) connection.





### Sustained Short Circuit = 230 Amps





### Sustained Short Circuit = 275 Amps

### Note 1

The following multiplication factors should be used to adjust the values from curve between time 0.001 seconds and the minimum current point in respect of nominal operating voltage:

50	Hz	60Hz				
Voltage	Factor	Voltage	Factor			
380v	X 1.00	416v	X 1.00			
400v	X 1.07	440v	X 1.06			
415v	X 1.12	460v	X 1.12			
440v	X 1.18	480v	X 1.17			

The sustained current value is constant irrespective of voltage level

### Note 2

The following multiplication factor should be used to convert the values calculated in accordance with NOTE 1 to those applicable to the various types of short circuit:

	3-phase	2-phase L-L	1-phase L-N
Instantaneous	x 1.00	x 0.87	x 1.30
Minimum	x 1.00	x 1.80	x 3.20
Sustained	x 1.00	x 1.50	x 2.50
Max. sustained duration	10 sec.	5 sec.	2 sec.

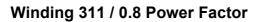
All other times are unchanged

#### Note 3

Curves are drawn for Star (Wye) connected machines. For other connection the following multipliers should be applied to current values as shown:

Parallel Star = Curve current value X 2

Series Delta = Curve current value X 1.732

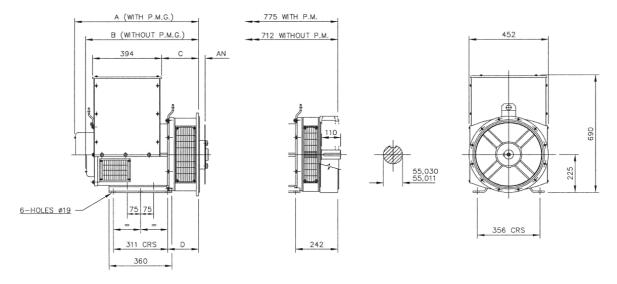




### **RATINGS**

	Class - Temp Rise	Cont. F - 105/40°C			Cont. H - 125/40°C			Standby - 150/40°C				Standby - 163/27°C					
50	Series Star (V)	380	400	415	440	380	400	415	440	380	400	415	440	380	400	415	440
	Parallel Star (V)	190	200	208	220	190	200	208	220	190	200	208	220	190	200	208	220
Hz	Series Delta (V)	220	230	240	254	220	230	240	254	220	230	240	254	220	230	240	254
	kVA	45.0	45.0	45.0	33.6	50.0	50.0	50.0	37.5	53.0	53.0	53.0	39.1	55.0	55.0	55.0	41.2
	kW	36.0	36.0	36.0	26.9	40.0	40.0	40.0	30.0	42.4	42.4	42.4	31.3	44.0	44.0	44.0	33.0
	Efficiency (%)	88.3	88.6	88.9	89.3	87.7	88.2	88.5	89.0	87.4	87.9	88.2	88.88	87.2	87.7	88.0	88.6
	kW Input	40.8	40.6	40.5	38.5	45.6	45.4	45.2	43.1	48.5	48.2	48.1	45.0	50.5	50.2	50.0	47.6
60	Series Star (V)	416	440	460	480	416	440	460	480	416	440	460	480	416	440	460	480
Hz	Parallal Star (\/)	208	220	230	240	208	220	230	240	208	220	230	240	208	220	230	240
' '2	- Delta (V)	240	254	266	277	240	254	266	277	240	254	266	277	240	254	266	277
	kVA	52.5	55.0	56.0	58.0	60.0	62.5	62.5	65.0	62.5	65.0	65.0	68.8	65.0	66.3	66.3	71.3
	kW	42.0	44.0	44.8	46.4	48.0	50.0	50.0	52.0	50.0	52.0	52.0	55.0	52.0	53.0	53.0	57.0
	Efficiency (%)	88.7	89.0	89.2	89.4	88.0	88.4	88.8	89.0	87.8	88.2	88.6	88.7	87.5	88.1	88.5	88.5
	kW Input	47.4	49.4	50.2	51.9	54.5	56.6	56.3	58.4	56.9	59.0	58.7	62.1	59.4	60.2	59.9	64.5

### **DIMENSIONS**



Γ	SINGLE BEARING MACHINES ONLY									
Γ	ADAPTOR	COUPLING DISCS	AN							
Γ	SAE 1	724,3	661,3	224,3	191,3	SAE 8	61,90			
Ī	SAE 2	710	647	210	177	SAE 10	53,98			
Γ	SAE 3	710	647	210	177	SAE 11,5	39,68			
Г	SAE 4	710	647	210	177	SAE 14	25.40			



